

Cell Segmentation and Tracking in Phase Contrast Images using Graph Cut with Asymmetric Boundary Costs

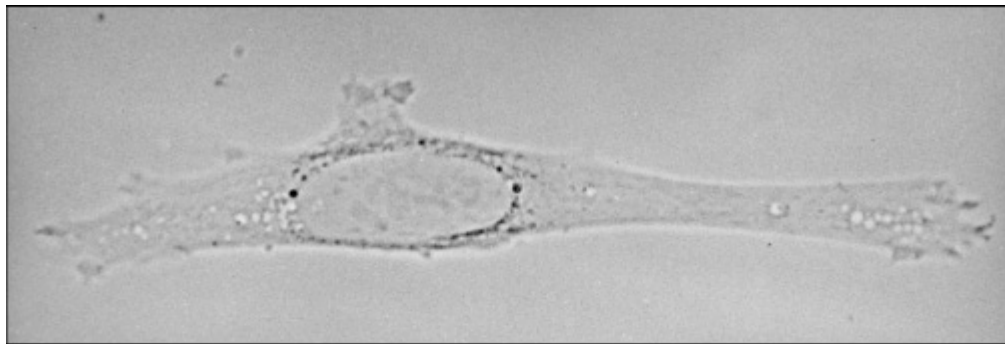
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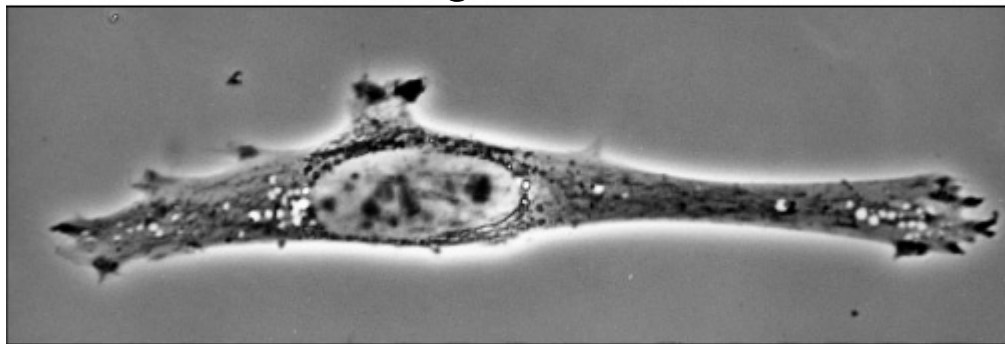


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April 16-19, Brooklyn, NY, USA

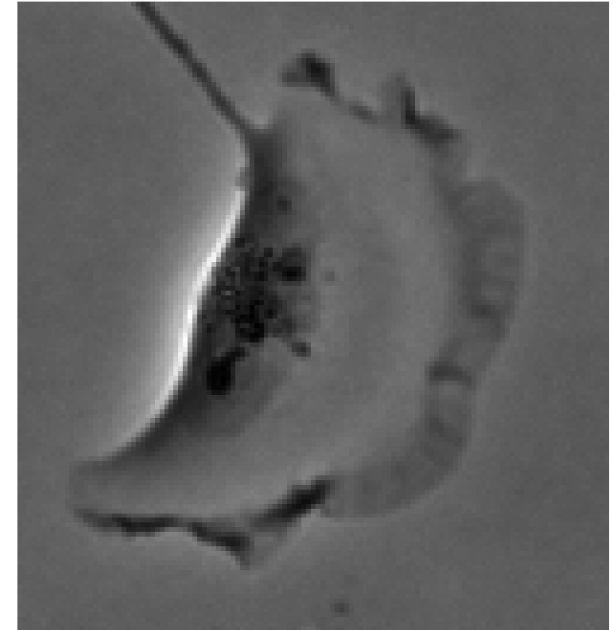
- Introduction
- Method
 - Segmentation
 - Tracking
- Experiments & Results
- Conclusion



(A) Bright-field



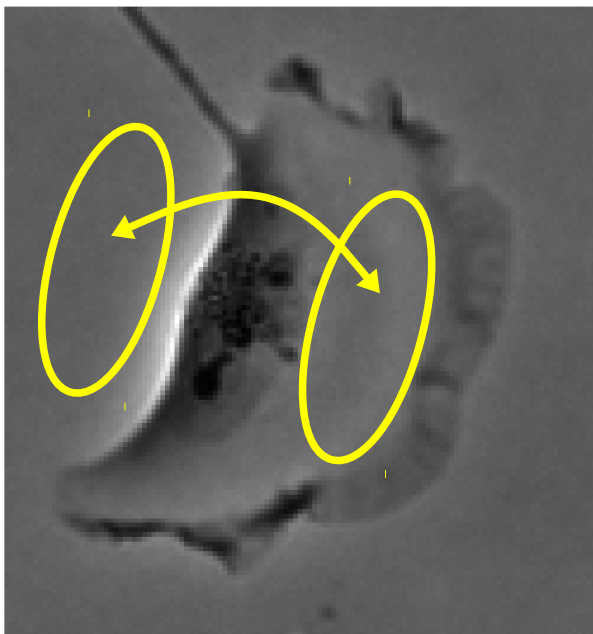
(B) Phase-contrast 50 μm



Phase-contrast

Figure: B. Alberts et al., Molecular Biology of the Cell, 4th Edition, 2002.

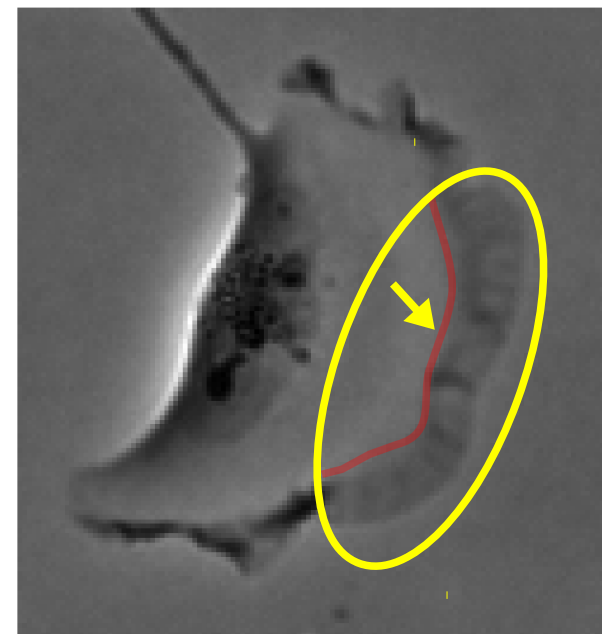
- **Visualize transparent objects** with high contrast at cell borders



Shade-off

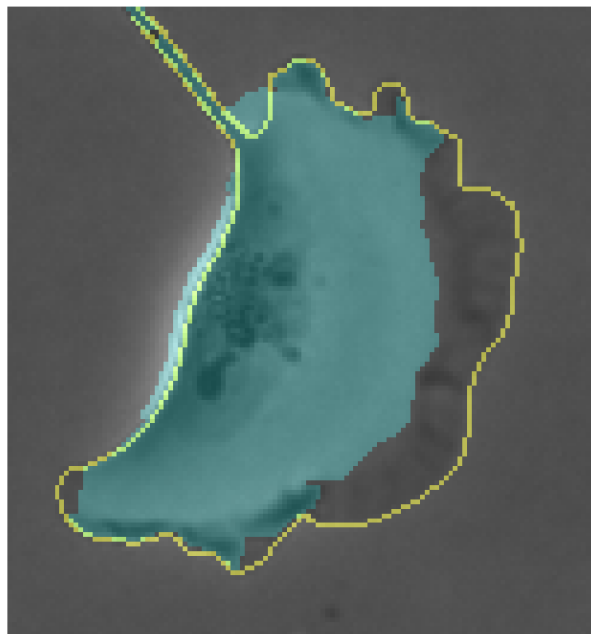


Halo pattern



Strong edges inside
and outside the cell

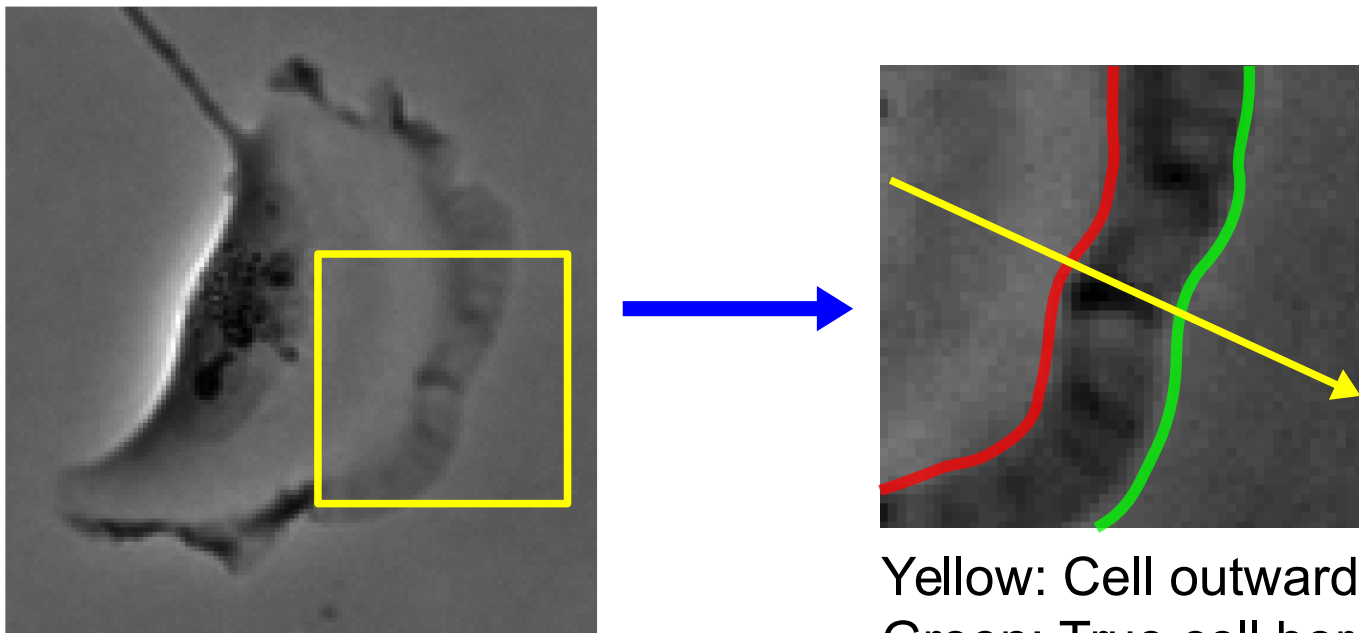
- Drawback: **Artifacts**



Cyan: Graph cut segmentation result
Yellow: Our manual ground truth

- Standard edge-based segmentation algorithms fail
- Traditional graph cut with **symmetric boundary costs**.

- True cell borders appear as **dark-to-bright** transition*



Yellow: Cell outwards direction
Green: True cell border
Red: Wrong cell border

(*positive phase contrast microscopy)

- Search for segmentation mask that favors dark-to-bright transitions at its boundary
- Graph cut with **asymmetric boundary costs**

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- Cost function (Region & boundary term)

$$E(M) = \lambda \cdot R(M) + \boxed{B(M)}$$

Mask $M : \Omega \rightarrow \{0, 1\}$,
 $\Omega \subset \mathbb{R}^2$

- Boundary term

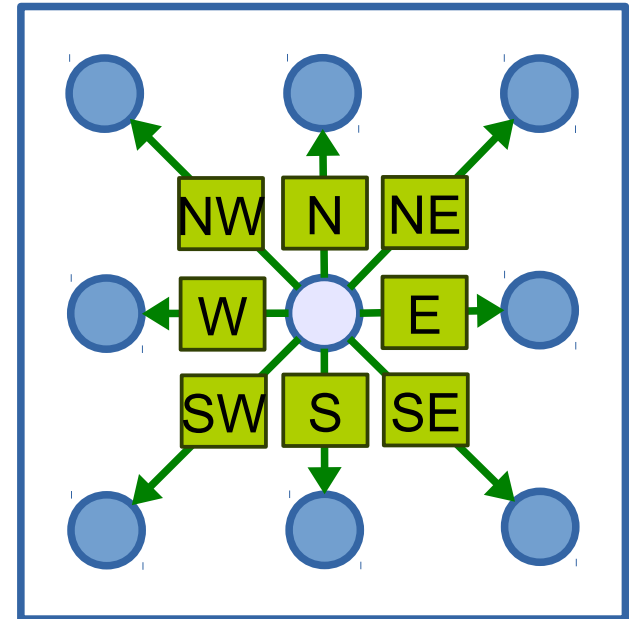
$$B(M) = \int_{\Omega} C_{\text{edge}} \left(\underbrace{\langle \nabla M(\mathbf{x}), -\nabla I(\mathbf{x}) \rangle}_{\substack{\text{intensity derivative } d \\ \text{(perpendicular to mask boundary)}}} \right) d\mathbf{x}$$

Image I
 ∇M unit normal vector
 on mask boundary, and
 $\mathbf{0}$ elsewhere

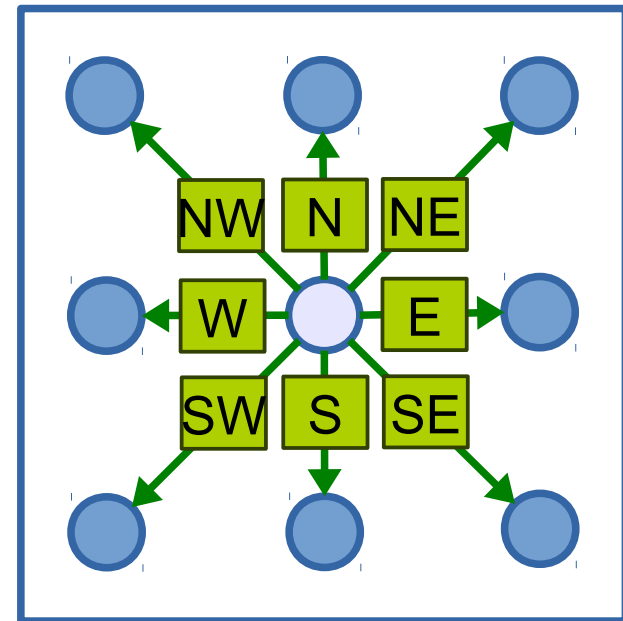
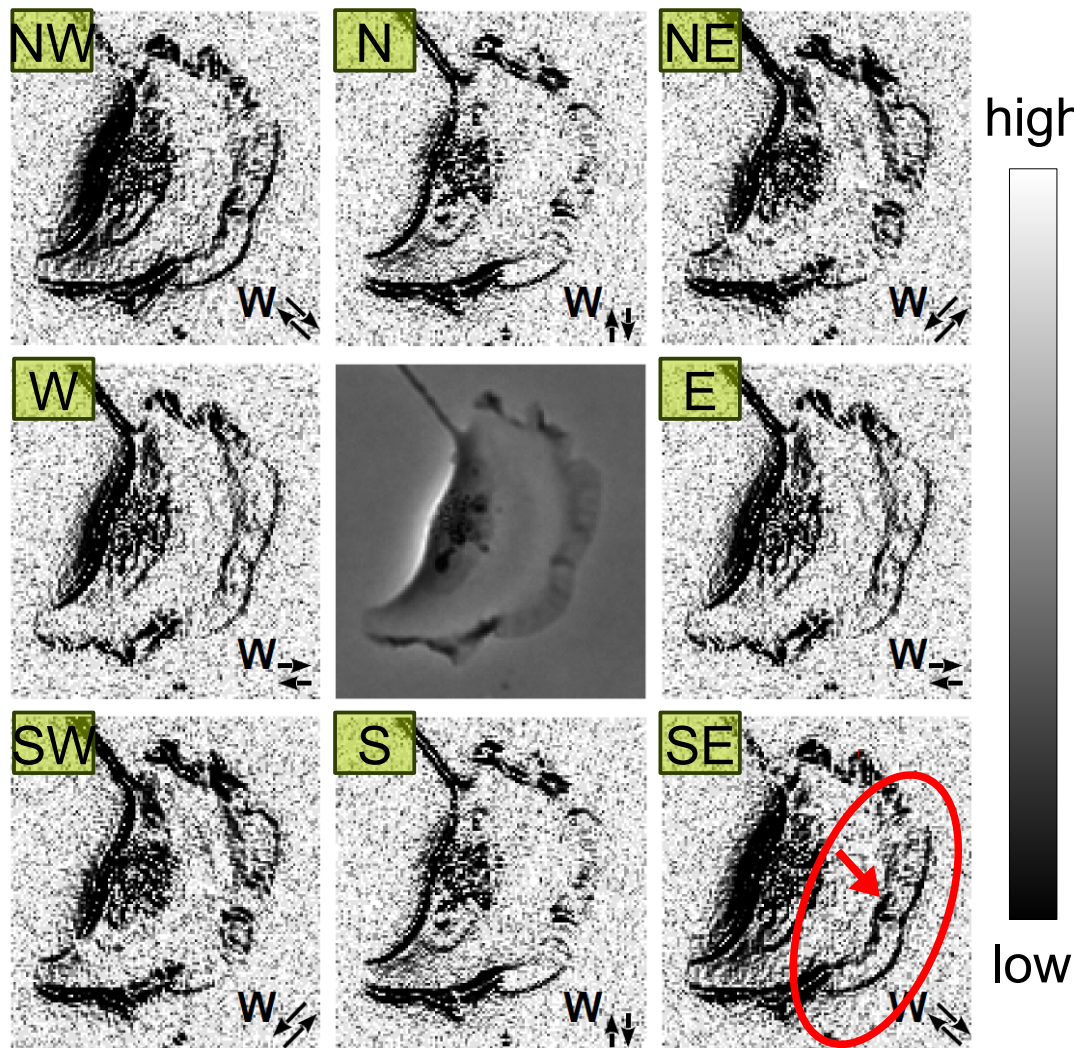
- **Asymmetric** boundary penalties (**dark-to-bright**)

$$C_{\text{edge}}(d) = \begin{cases} \exp\left(-\frac{d^2}{2\sigma^2}\right) & \text{if } \boxed{d > 0} \\ 1 & \text{else.} \end{cases}$$

→ **directed graph**
 with asymmetric
 edge weights

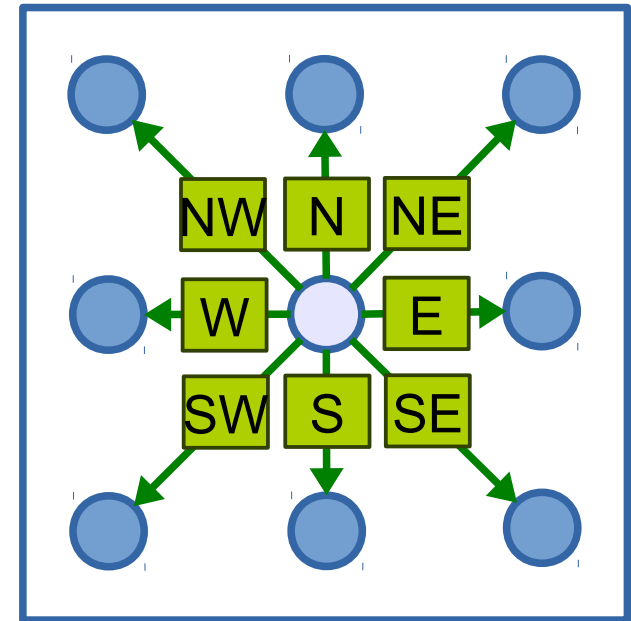
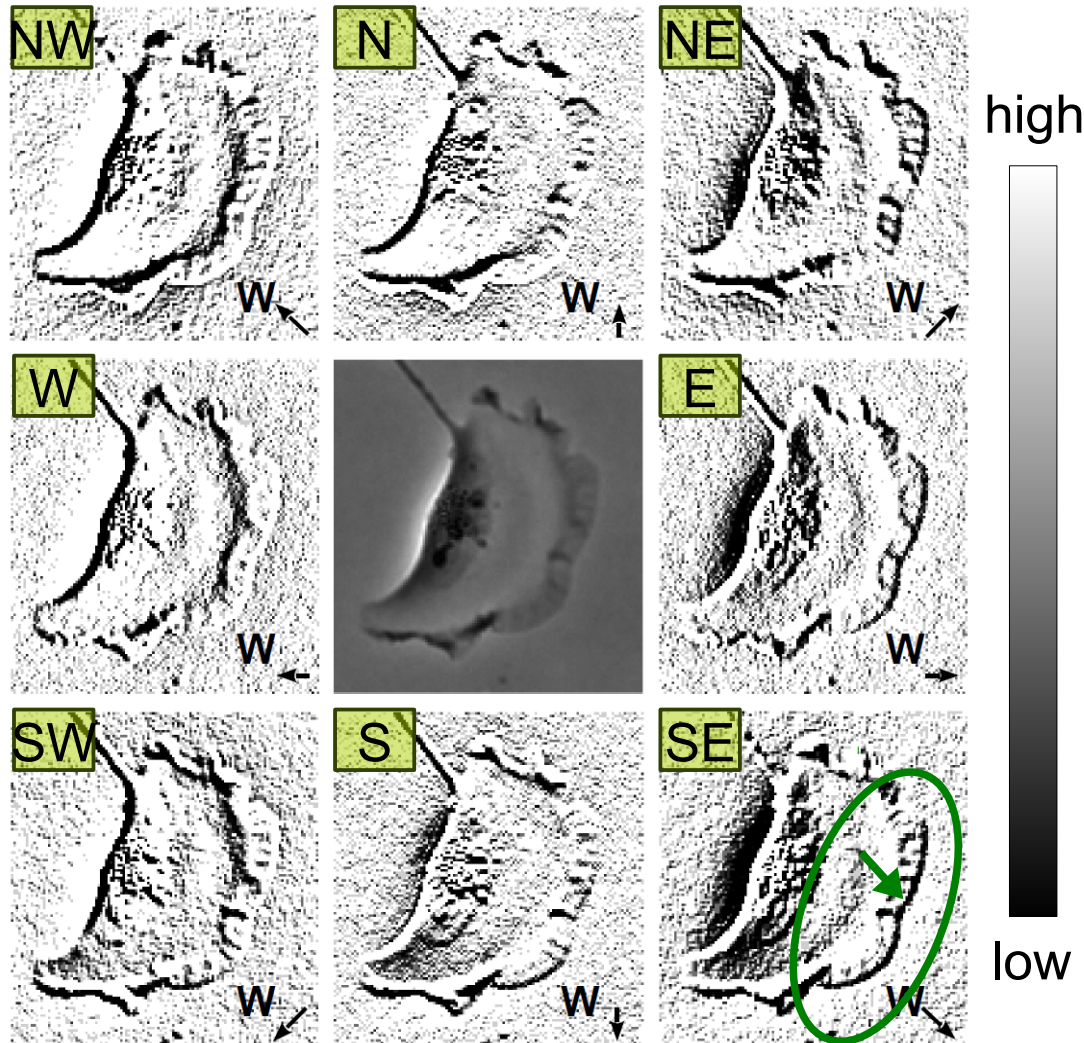


3x3 pixel neighborhood,
Edges and weights (only
outwards edges shown)



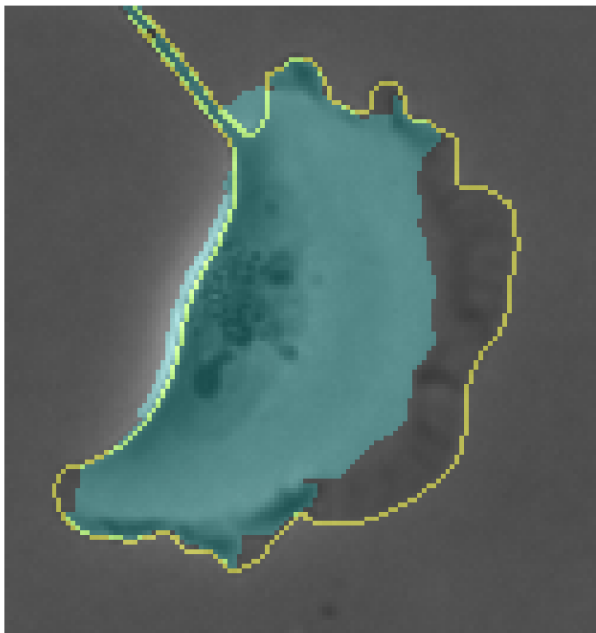
3x3 pixel neighborhood,
Edges and weights (only
outwards edges shown)

- Low costs at **wrong cell borders**
(bright-to-dark transitions)

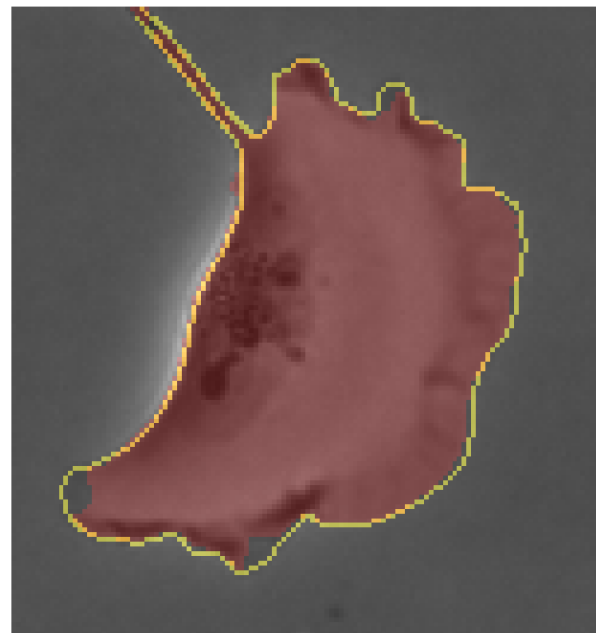


3x3 pixel neighborhood,
Edges and weights (only
 outwards edges shown)

- Low costs at **correct cell borders**
 (dark-to-bright transitions)



Cyan mask: Segmentation result of graph cut with **symmetric costs**
Yellow: Our manual ground truth



Red mask: Segmentation result of **proposed method**
Yellow: Our manual ground truth

- Standard graph cut

$$R(A) = \sum_{p \in \mathcal{P}} R_p(A_p) \quad (\text{regional term})$$

$$R_p(\text{"obj"}) = -\ln \Pr(I_p | \text{"obj"}) \quad (\text{object penalty})$$

$$R_p(\text{"bkg"}) = -\ln \Pr(I_p | \text{"bkg"}) \quad (\text{background penalty})$$

→ **hard constraint**

- In our approach

$$R(M) = \int_{\Omega} M(\mathbf{x}) \cdot C_{\text{obj}}(I(\mathbf{x})) d\mathbf{x} \quad (\text{regional term})$$

$$C_{\text{obj}}(v) = \frac{P(v|\mathcal{B}) - P(v|\mathcal{O})}{P(v|\mathcal{O}) + P(v|\mathcal{B})} \quad (\text{data costs})$$

Intensity v

$P(v|\mathcal{O})$ and $P(v|\mathcal{B})$

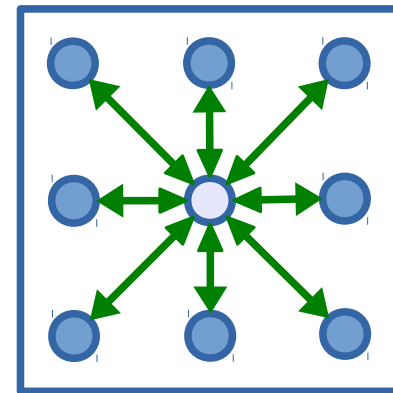
from fore-/background

intensity histograms

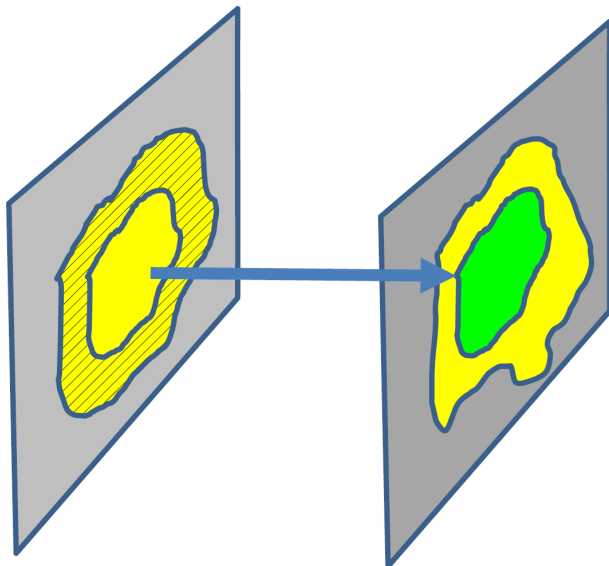
→ **soft constraint**

$$\begin{aligned}
 E(M) = & \lambda \int_{\Omega} M(\mathbf{x}) \cdot C_{\text{obj}}(I(\mathbf{x})) d\mathbf{x} \\
 & + \int_{\Omega} C_{\text{edge}} (\langle \nabla M(\mathbf{x}), -\nabla I(\mathbf{x}) \rangle) d\mathbf{x}
 \end{aligned}$$

- Energy minimization problem
- Discretize edge term into 8 directions
→ combinatorial optimization problem
- Solve efficiently by a **min-cut approach**

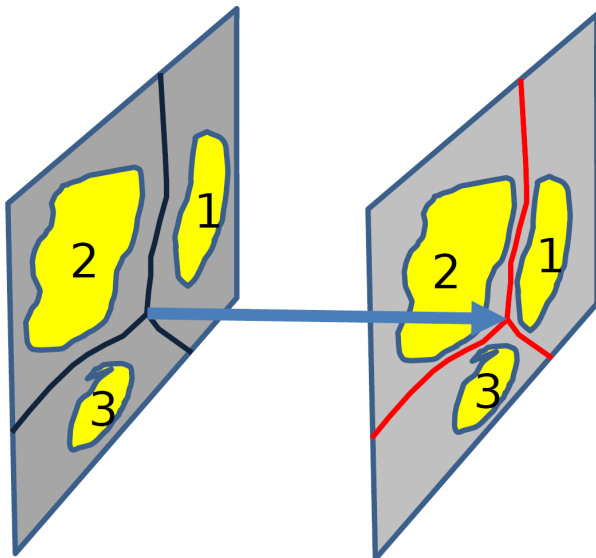


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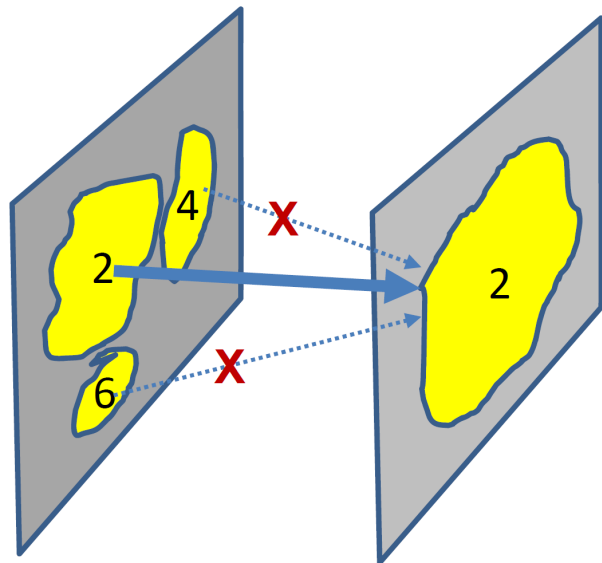
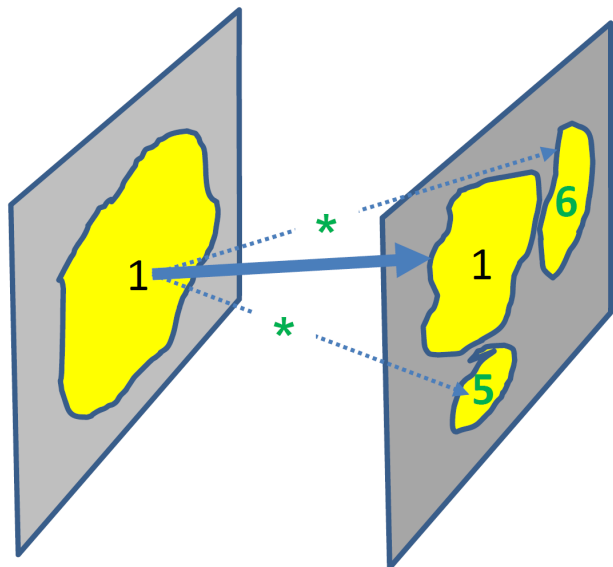


- Propagate Segmentation Information

- **Foreground information** using eroded mask
→ foreground constraint



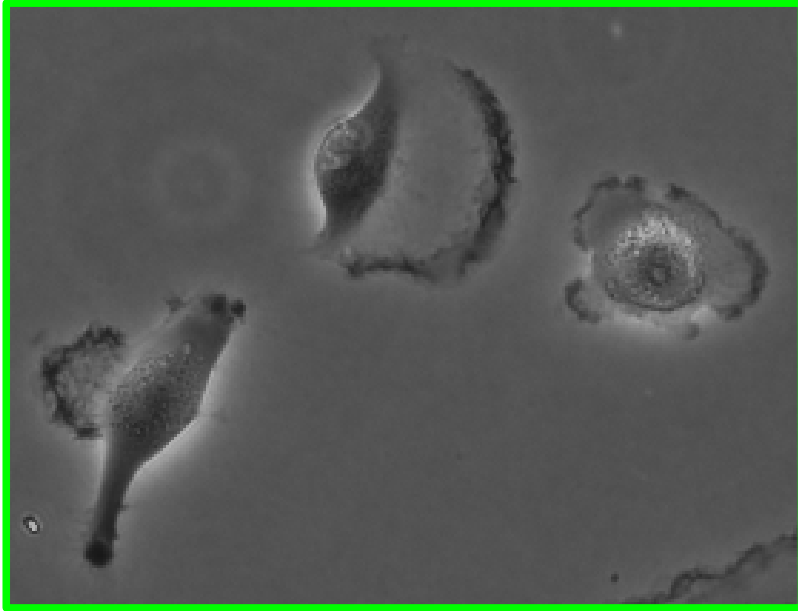
- **Partitioning information** using borders of „support regions“
→ background constraint



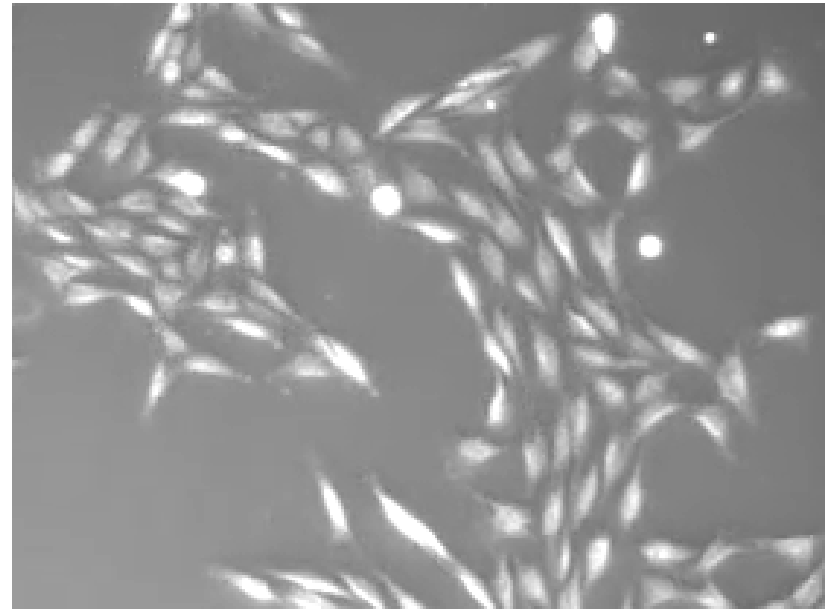
- Propagate Labels to overlapping Segments
- Resolve **one-to-many** correspondences
 - Propagate label to max. IOU
 - Invent new labels
- Resolve **many-to-one** correspondences
 - Take label from max. IOU
 - Kill other labels

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Datasets: ISBI cell tracking challenge^{1,2}



Glioblastoma-astrocytoma U373 cells on a polyacrylimide substrate*



Pancreatic Stem Cells on a Polystyrene substrate (2D)[†]

- Strong shape variations
- Weak outer borders, strong irrelevant inner borders
- Cytoplasm has same structure as background

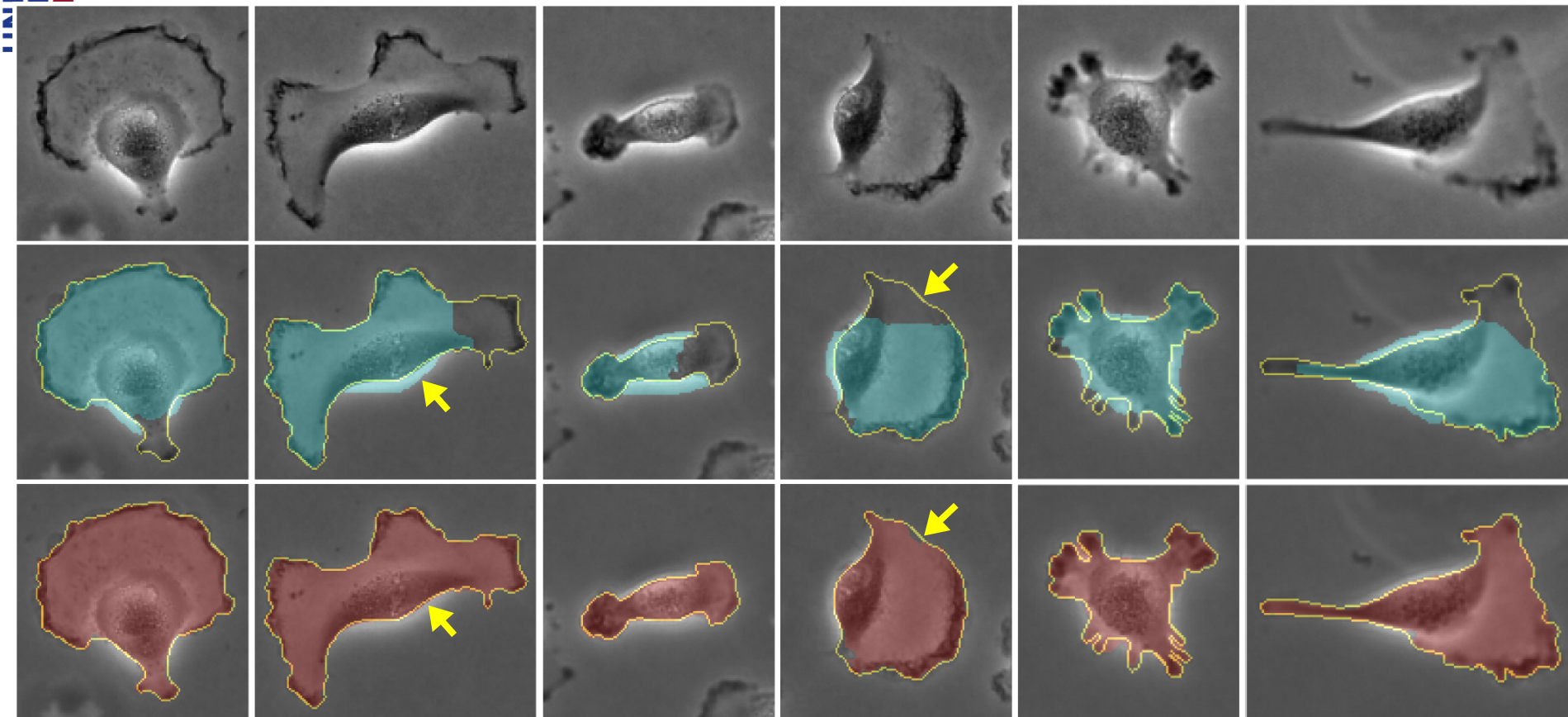
(1) ISBI Cell Tracking Challenge, Available at: <http://www.codesolorzano.com/celltrackingchallenge>.

(2) M. Maška, V. Ulman, D. Svoboda, P. Matula, and P. Matula, et al., “A benchmark for comparison of cell tracking algorithms,” *Bioinformatics*, vol. 30, no. 11, pp. 1609–1617, 2014.

*Data provided by Dr. Sanjay Kumar. Department of Bioengineering University of California at Berkeley. Berkeley CA (USA).

†Data provided by Dr. Tim Becker. Fraunhofer Institution for Marine Biotechnology. Lübeck. Germany

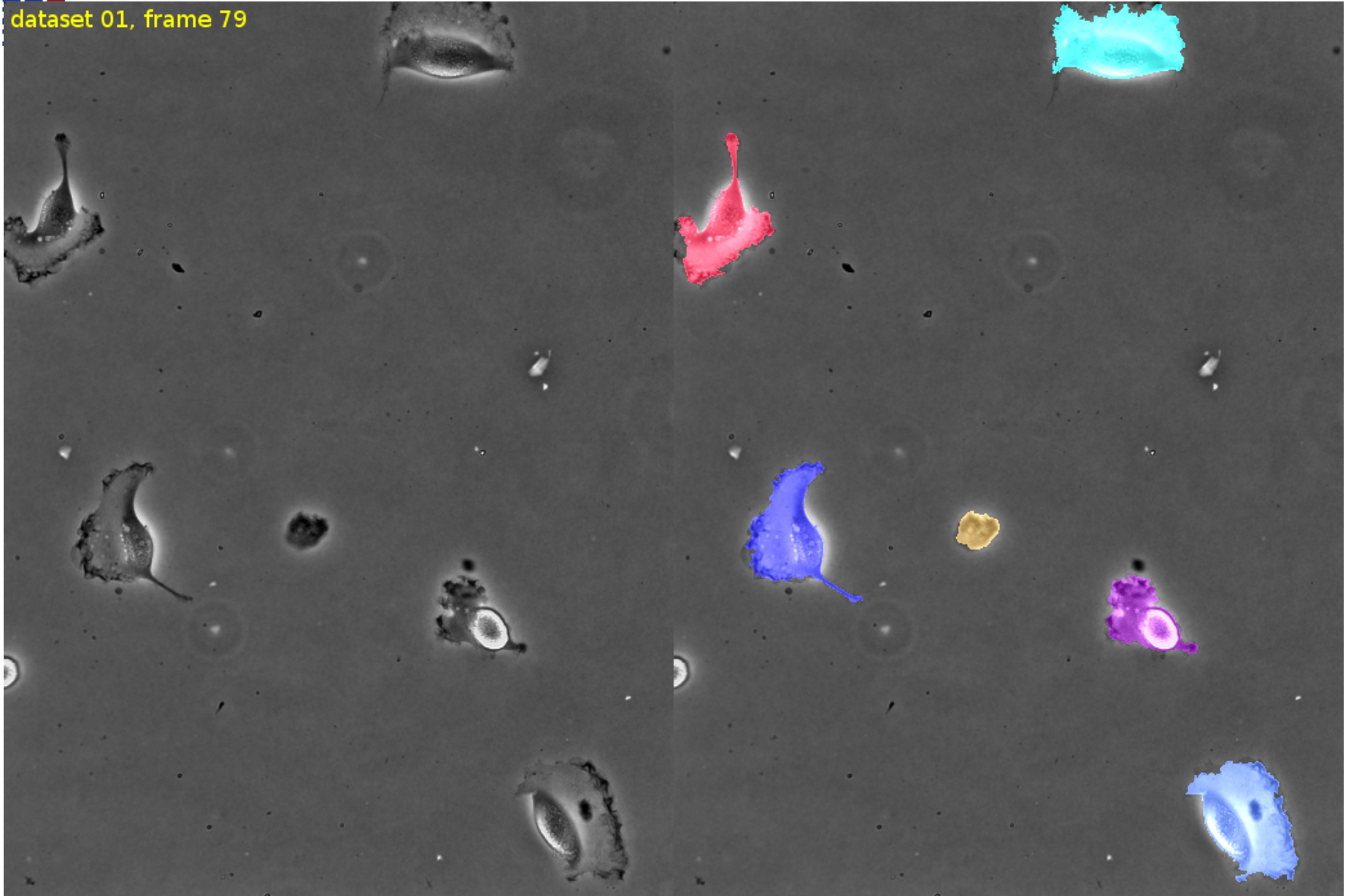
Experiments: Symmetric vs. asymmetric costs



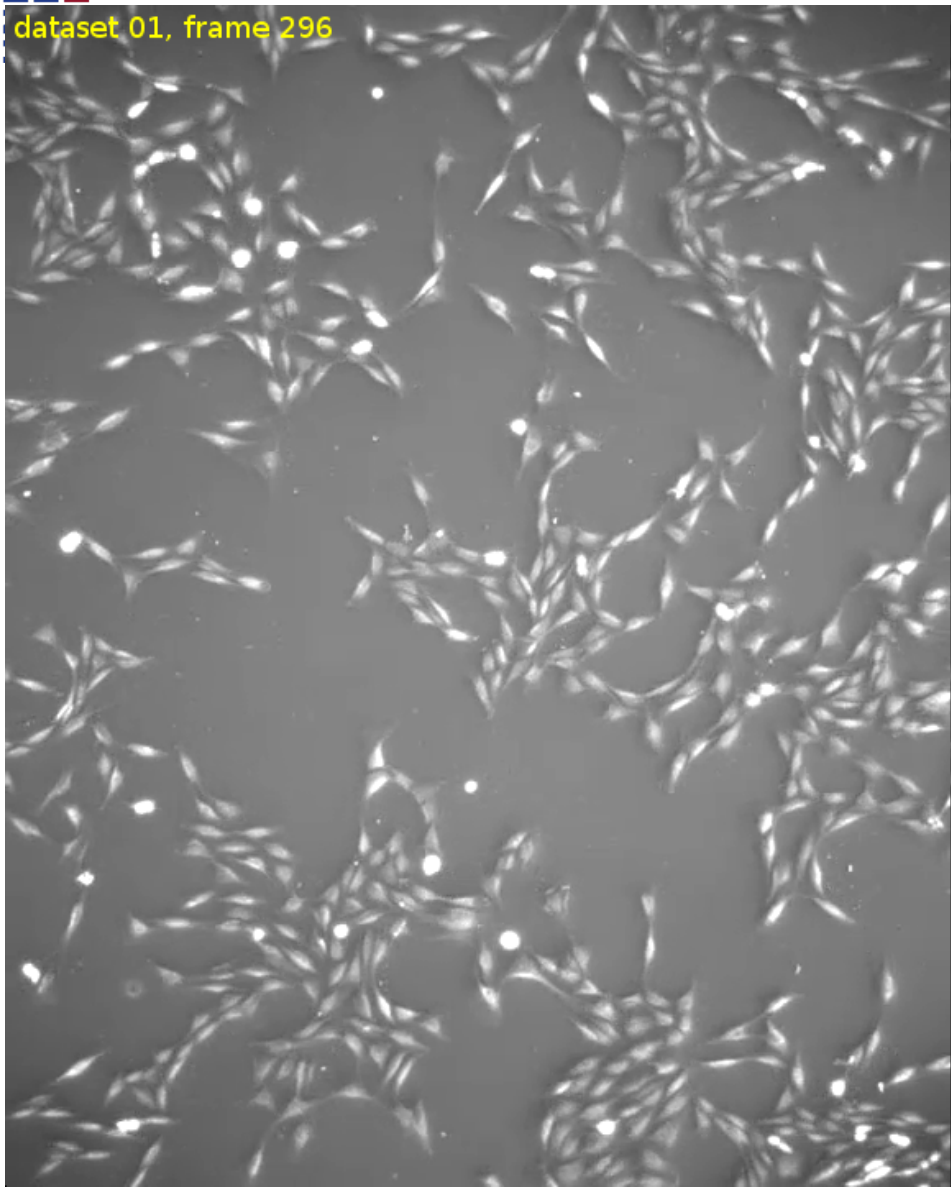
Cyan masks: Graph cut with symmetric costs, Red masks: Our approach with asymmetric costs, Yellow borders: Our manual ground truth

- Improved detection of very **weak boundaries**
- **Halo boundaries** are handled well

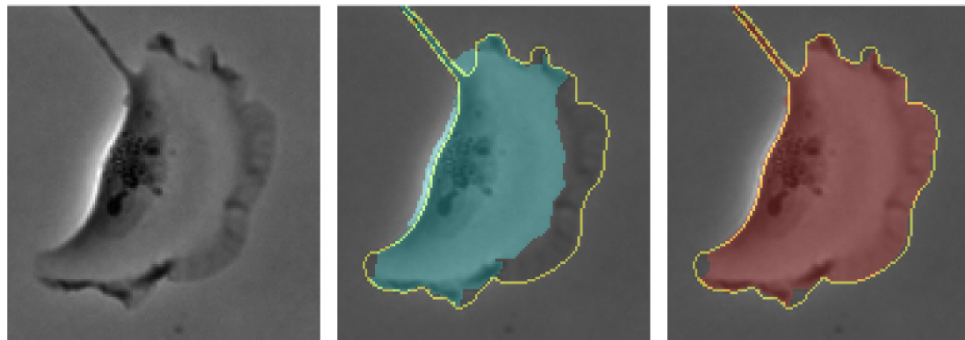
dataset 01, frame 79



dataset 01, frame 296



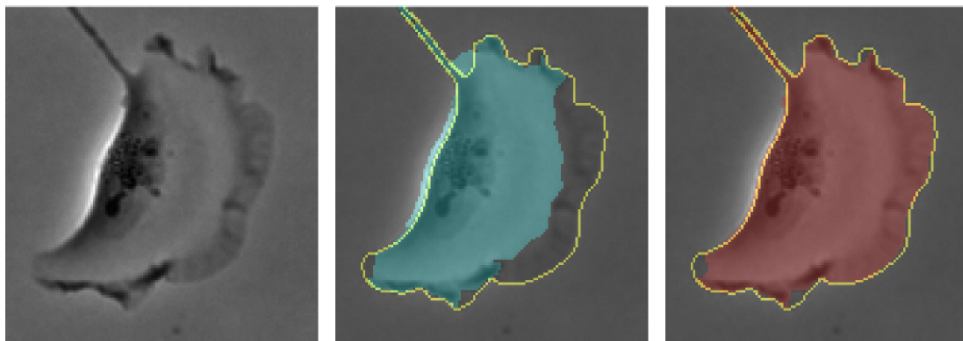
- Direction dependent boundary costs improve segmentation in phase contrast microscopy
 - Our approach outperforms standard min-cut segmentation with symmetric costs
- *Profit for cell segmentation in other modalities*
- *Open-source MATLAB code (and ImageJ plugin)*:*
<http://lmb.informatik.uni-freiburg.de/resources/opensource/CellTracking/>



*(coming soon ;)

Thank you!

- *Talk on Saturday, April 18, 14:45–15:00, Session: Segmentation for Microscopy Imaging – SaCT4, Room: Salon C*
- *Open-source MATLAB code (and ImageJ plugin)*:*
<http://lmb.informatik.uni-freiburg.de/resources/opensource/CellTracking/>



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