Vector Quantization in Content Based Image Retrieval

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Contents

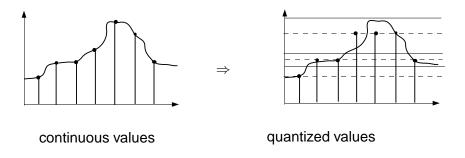
- Introduction in VQ
 - Quantization
 - Vector Quantization
 - VQ Advantage
- VQ Algorithms
 - Generalized Lloyd Algorithm (GLA)
 - Tree-structured Codebook Representation
- VQ detailed
 - Trainingset
 - Problems of VQ
- Implementation
 - Range Normalization
 - Partial Distance Search
- Test Results
 - first PR-Graph
 - Feature Enhencement



- Quantization
- Vector Quantization
- VQ Advantage
- VQ Algorithms
 - Generalized Lloyd Algorithm (GLA)
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 - Trainingset
 - Problems of VQ
- - Range Normalization
 - Partial Distance Search
- - first PR-Graph
 - Feature Enhancement



Quantization



quantization = continuous values mapped to distribution representative values

00000

VQ formal[Theodoridis]

$$Q: R^k \to C = \{c_1, \dots, c_i, \dots, c_n\} | c \in R^k\}$$

C = codebook, n = codebook size and $c_i = \text{codewords}$

For given $T = \{t_1, \dots, t_i, \dots, t_m\} \subseteq R^k$ (trainingset) Q creates partition of T

$$P = \{p_1, \ldots, p_i, \ldots, p_n\}$$

with
$$p_i = \{t | t \in T \land Q(t) = c_i\}$$

Optimal Vector Quantizer [Zhu]

A optimal quantizer has two conditions:

Nearest Neighbor Condition:
 For each p_i, if

$$t \in p_i$$
 : $d(t, c_i) \leq d(t, c_j) \quad \forall j \neq i$

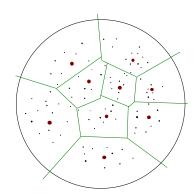
Centroid Condition: Given P

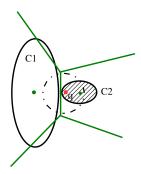
$$c_i = \frac{\sum\limits_{t \in p_i} t}{k_i},$$

where k_i is the cardinality of p_i .

VQ is used for:

- Encoding (loosely)
- Clustering (⇒ classification)





(q Query feature - dashed circle = normal retrieval - hatched area = VQ retrieval)



Contents

- 1 Introduction in VQ
 - Quantization
 - Vector Quantization
 - VQ Advantage
- VQ Algorithms
 - Generalized Lloyd Algorithm (GLA)
 - Tree-structured Codebook Representation
- VQ detailed
 - Trainingset
 - Problems of VQ
- 4 Implementation
 - Range Normalization
 - Partial Distance Search
- Test Results
 - first PR-Graph
 - Feature Enhencement



populated Algoritms are:

- Generalized Lloyd Algorithm (GLA)
- Pairwise Nearest Neighbour Algorithm (PNNA)
- Hierarchical, Fuzzy, ...

Generalized Lloyd Algorithm (GLA)

GLA

- Given a training set $T = \{t_1, \ldots, t_m\}$, initial codebook $C_1 = \{c_1, \ldots, c_n\}$ and a threshold δ .
- 2 Use C_k to get the partition P based on *nearest neighbor condition*, and compute the average distortion.

$$D_k = \frac{\sum\limits_{i=1}^n \sum\limits_{t \in p_i} d(t, c_i)}{m}$$

where m is the number of images in the partition P and n the codebook size.

- **3** If $\frac{D_{k-1}-D_k}{D_k} \leq \delta$, stop the iteration. C_k would be the final codebook.
- **③** Create a new codebook C_{k+1} by using the *centroid condition* with partition P.
- Increase the iteration and go on with point 2.

Tree-structured Codebook Representation

The Tree-structured Codebook is a binary tree with decisively vectors in the nodes and codewords in the leafs.[Cosman]

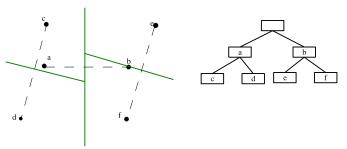
How to quantize with Tree-structured Codebook

- Given vector v, start at root

$$d_l = d(v, n_l)$$
 $d_r = d(v, n_r)$

If $d_1 < d_r$ select the right branch, else select the left branch.

3 go on with point 2 until the leaf is reached

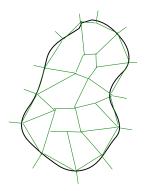


Contents

- 1 Introduction in VQ
 - Quantization
 - Vector Quantization
 - VQ Advantage
 - VQ Algorithms
 - Generalized Lloyd Algorithm (GLA)
 - Tree-structured Codebook Representation
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A good quantization of a class looks like this



Therefor

- codewords which approximate class distribution
- good codebook size

necessary



Trainingset

The codebook is created with the trainingset, a subset of the database.

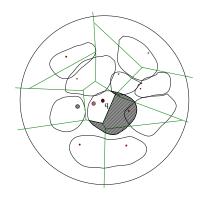
The trainingset should approximate the class distribution.



- a-priori knowledge of the classes necessary
- or calculate density distribution of trainingset.

Best: trainingset = database.

small codebook size⇒



misclassifi cation

too high codebook size ⇒ zero codewords
 (zero codeword = cluster without vectors)
 Solution: Reinitiate codewords with random vectors at the codebook generation

Contents

- 1 Introduction in VQ
 - Quantization
 - Vector Quantization
 - VQ Advantage
 - VQ Algorithms
 - Generalized Lloyd Algorithm (GLA)
 - Tree-structured Codebook Representation
- VQ detailed
 - Trainingset
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- Implementation
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 - Partial Distance Search
- Test Results
 - first PR-Graph
 - Feature Enhencement



Test Implementation

contains:

- GLA
- Reinitialization of zero codewords with random vectors
- Normalization over the range for weighting
- Partial Distance Search

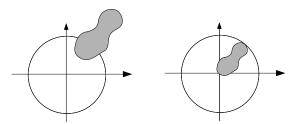
Range Normalization

For combining different feature types the feature types have to bee normalized.

To conserve the class shape I used the normalization over the range.

$$\hat{f} = \frac{f - f_{min}}{||f_{max} - f_{min}||}$$

(with $||f_{min}|| \le ||f||$ and $||f_{max}|| \ge ||f||$) computed for every feature type



Partial Distance Search

```
index = 1;

d_{min} = (x - c_i)^2;

for i = 2 to n do

d = 0;

for j = 1 to m do

d = d + (x(j) - c_i(j))^2;

if (d > d_{min}) break; end

end

! if (d < d_{min})

d_{min} = d;

index = i;

end

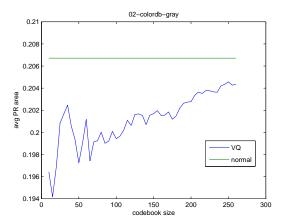
end
```

Contents

- 1 Introduction in VQ
 - Quantization
 - Vector Quantization
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first PR-Graph



Feature Enhencement

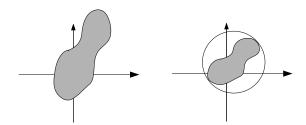
Normalization by the standard deviation of the class

$$f=(f_1,\ldots,f_n)$$

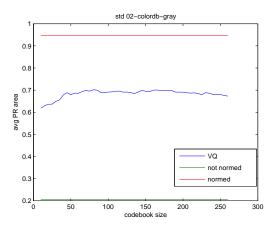
K : feature space → class

 $S: class \rightarrow \sigma = (\sigma_1, \ldots, \sigma_n)$

$$\hat{f} = \left(\frac{f_i}{S(K(f))_i}, \dots, \frac{f_n}{S(K(f))_n}\right)$$



Feature Enhencement



Frequency matrix F

class \ cluster	1	2	3	4
а	0	4	0	0
b	1	2	5	2
С	3	1	0	0
d	0	2	6	3

class a complete in cluster 2 class b is very big

class d lays on b and has high density

The count of features for class x in cluster c



Introduction in VQ

Evaluation 1/2

mis-classification by classes

$$m1(c) = \frac{\sum_{i} F(c,i) - \max_{i} (F(c,i))}{\max_{i} (F(c,i))}$$
$$= 1 - \frac{\max_{i} (F(c,i))}{\max_{i} (F(c,i))}$$



mis-classification by clusters

$$m2(c) = 1 - \frac{\max_{i}(F(i,c))}{\max_{i}(F(i,c))}$$

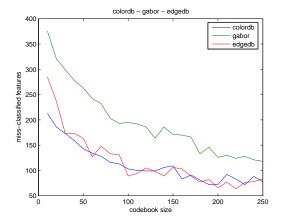


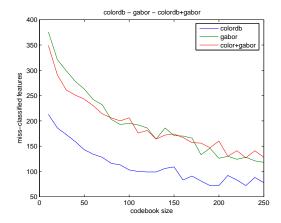
Evaluation 2/2

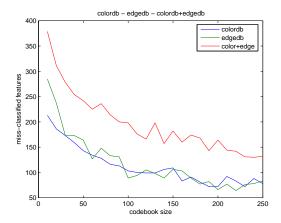
codebook quality

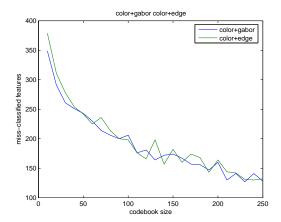
$$\sum_{i} \left(\left(\sum_{j} F(j, i) \right) - \max_{k} F(k, i) \right)$$

(assumption: more cluster than classes)









References:

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K.L. Oehler, E.A. Riskin, R.M. Gray; IEEE 1993

[Zuh]: "Keyblock: An Approach for Content-based Image Retrieval" L. Zhu, A. Zhang, A. Rao, R. Srihari; SUNY at Buffalo

